



## **MCH Series Drives** LonWorks Communications Guide

## ***About These Instructions***

This documentation applies to the use of an MCH Series Variable Frequency Drive with LonWorks protocol and should be used in conjunction with the MCH Series Installation and Operation Manual (Document MH01) that shipped with the drive. These documents should be read in their entirety as they contain important technical data and describe the installation and operation of the drive.

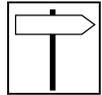
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1	Safety Information.....	1
1.1	Warnings, Cautions and Notes .....	1
1.1.1	General .....	1
1.1.2	Application .....	1
1.1.3	Installation .....	1
1.1.4	Electrical Connection.....	2
1.1.5	Operation .....	2
2	Introduction.....	3
2.1	Hardware Description .....	3
2.2	LED Status Indicators.....	4
2.3	Serial Communications Wiring .....	5
3	Drive Setup and Programming.....	6
3.1	Added Programming Parameters .....	6
3.2	Bus Configuration Parameters.....	7
3.3	Omitted Parameters and Selections .....	9
3.4	Modified Parameters and Selections .....	9
3.5	Serial Communication Setup.....	10
4	MCH LonWorks® Network Variables .....	12
4.1	LonWorks® Network Variable Map .....	12
4.2	Supported Input Network Variables .....	13
4.3	Supported Output Network Variables.....	15
4.4	Supported Configuration Network Variables .....	19
4.5	LonWorks XIF Files .....	23



## 1 Safety Information

### 1.1 Warnings, Cautions and Notes

#### 1.1.1 General

Some parts of Lenze controllers (frequency inverters, servo inverters, DC controllers) can be live, moving and rotating. Some surfaces can be hot.

Non-authorized removal of the required cover, inappropriate use, and incorrect installation or operation creates the risk of severe injury to personnel or damage to equipment.

All operations concerning transport, installation, and commissioning as well as maintenance must be carried out by qualified, skilled personnel (IEC 364 and CENELEC HD 384 or DIN VDE 0100 and IEC report 664 or DIN VDE0110 and national regulations for the prevention of accidents must be observed).

According to this basic safety information, qualified skilled personnel are persons who are familiar with the installation, assembly, commissioning, and operation of the product and who have the qualifications necessary for their occupation.

#### 1.1.2 Application

Drive controllers are components designed for installation in electrical systems or machinery. They are not to be used as appliances. They are intended exclusively for professional and commercial purposes according to EN 61000-3-2. The documentation includes information on compliance with EN 61000-3-2.

When installing the drive controllers in machines, commissioning (i.e. the starting of operation as directed) is prohibited until it is proven that the machine complies with the regulations of the EC Directive 98/37/EC (Machinery Directive); EN 60204 must be observed.

Commissioning (i.e. starting drive as directed) is only allowed when there is compliance to the EMC Directive (89/336/EEC).

The drive controllers meet the requirements of the Low Voltage Directive 73/23/EEC. The harmonised standards of the series EN 50178/DIN VDE 0160 apply to the controllers.

**The availability of controllers is restricted according to EN 61800-3. These products can cause radio interference in residential areas. In the case of radio interference, special measures may be necessary for drive controllers.**

#### 1.1.3 Installation

Ensure proper handling and avoid excessive mechanical stress. Do not bend any components and do not change any insulation distances during transport or handling. Do not touch any electronic components and contacts. Controllers contain electrostatically sensitive components, which can easily be damaged by inappropriate handling. Do not damage or destroy any electrical components since this might endanger your health! When installing the drive ensure optimal airflow by observing all clearance distances in the drive's user manual. Do not expose the drive to excessive: vibration, temperature, humidity, sunlight, dust, pollutants, corrosive chemicals or other hazardous environments.



# Safety Information

## 1.1.4 Electrical Connection

When working on live drive controllers, applicable national regulations for the prevention of accidents (e.g. VBG 4) must be observed.

The electrical installation must be carried out in accordance with the appropriate regulations (e.g. cable cross-sections, fuses, PE connection). Additional information can be obtained from the regulatory documentation.

The regulatory documentation contains information about installation in compliance with EMC (shielding, grounding, filters and cables). These notes must also be observed for CE-marked controllers.

The manufacturer of the system or machine is responsible for compliance with the required limit values demanded by EMC legislation.

## 1.1.5 Operation

Systems including controllers must be equipped with additional monitoring and protection devices according to the corresponding standards (e.g. technical equipment, regulations for prevention of accidents, etc.). You are allowed to adapt the controller to your application as described in the documentation.



**DANGER!**

- After the controller has been disconnected from the supply voltage, do not touch the live components and power connection until the capacitors have discharged. Please observe the corresponding notes on the controller.
- Do not continuously cycle input power to the controller more than once every three minutes.
- Close all protective covers and doors during operation.



**WARNING!**

Network control permits automatic starting and stopping of the inverter drive. The system design must incorporate adequate protection to prevent personnel from accessing moving equipment while power is applied to the drive system.

Table 1: Pictographs used in these instructions

Pictograph	Signal word	Meaning	Consequences if ignored
	<b>DANGER!</b>	Warning of Hazardous Electrical Voltage.	Reference to an imminent danger that may result in death or serious personal injury if the corresponding measures are not taken.
	<b>WARNING!</b>	Impending or possible danger for persons	Death or injury
	<b>STOP!</b>	Possible damage to equipment	Damage to drive system or its surroundings
	<b>NOTE</b>	Useful tip: If observed, it will make using the drive easier	



## 2 Introduction

This document explains how to connect an MCH Drive to a LonWorks® network. It is intended as a serial communications supplement only and will not discuss normal drive operations. For more information regarding normal drive setup and functionality, refer to the MCH Installation and Operation Manual (MH01).

LonWorks® technology is a complete platform for implementing control network systems. These networks consist of intelligent control devices or nodes that interact with their environment and communicate with each other using a common, message based protocol (LonTalk®). A LonWorks® network can consist of up to 32,385 nodes divided into 255 subnets (127 nodes/subnet).

### 2.1 Hardware Description

To connect to a LonWorks® network, the MCH Drive utilizes an Anybus-S® Drive Profile Embedded Interface Card that supports Version 1.1 of the LonMark® 6010 Functional Profile for Variable Speed Motor Drives. This Anybus-S LonWorks (ABS-LON®) module is located inside of the bypass or option box that is attached to the MCH Drive.

The ABS-LON® module communicates according to the LonTalk® protocol. This means that it can communicate with all LonWorks® nodes that comply with this protocol, but it does not necessarily mean that all services available in the LonTalk® protocol are supported.

The ABS-LON® module uses the FTT-10A (Free Topology Twisted Pair) transceiver from Echelon Corporation. This is the most commonly used twisted-pair media in building automation and this architecture supports star, bus and loop wiring. The FTT-10A transceiver connects to a twisted pair cable with a baud rate of 78 kbit/s. The FTT-10A transceiver appears as a high impedance to the network when unpowered, and does not interfere with network communications when powered down.

Figure 1 identifies the components of the communications module intended for user interaction.

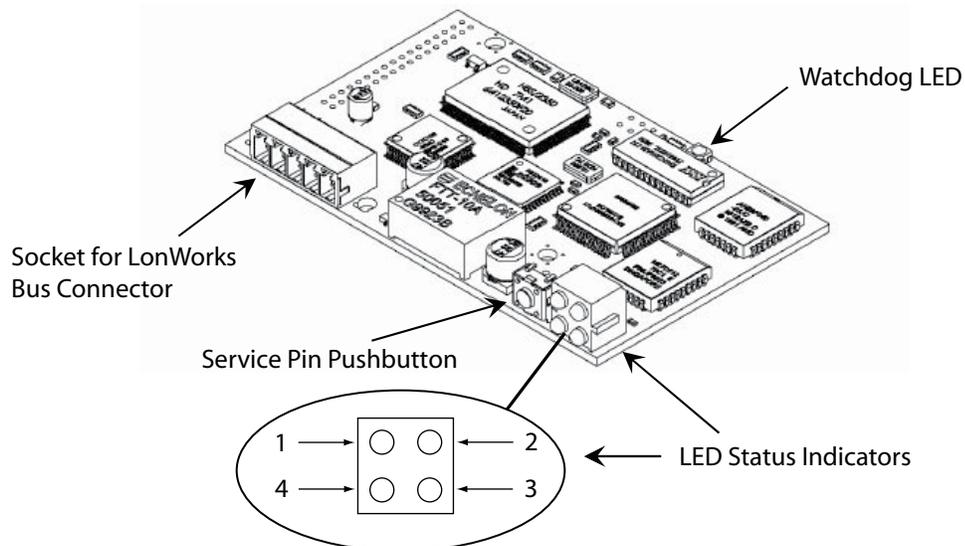
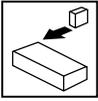


Figure 1: MCH LonWorks® Comm Module



# Drive Setup & Programming

## 2.2 LED Status Indicators

### LED 1 - Drive Communication

This LED indicates the communication status between the comm module and the drive.

LED State	Indicates:
Steady Green	Link OK
Steady Red	Link lost, permanent
Flashing Red	Link lost, temporary

### LED 2 - Service

This LED indicates the node configuration and application status.

LED State	Indicates:
Steady OFF	Node configured and installed in network
Steady Green	Node not configured, has no application; Error detected by Neuron Self Test routine
Flashing Green	Node not configured and not installed in network but node has an application

### LED 3 - Wink

This LED indicates receipt of a wink command.

LED State	Indicates:
Flashing Red	Wink command received on LonWorks® network
Steady OFF	Normal state

### LED 4 - Network Status

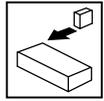
This LED indicates the communication status between the module and the LonWorks® network.

LED State	Indicates:
Steady OFF	No power
Flashing Red	Receive heartbeat timeout occurred; Fieldbus communication loss indicated to host: RX_FAIL
Steady Green	Module and network are communicating correctly

### Watchdog LED (WD)

This LED indicates module, drive and software status.

LED State	Indicates:
Flashing Green 1Hz	Module initialized and running properly
Flashing Green 2Hz	Module not initialized
Flashing Red 1Hz	Hardware check fault
Flashing Red 4Hz	Drive initialization failed
Steady Orange	Software download enabled



## 2.3 Serial Communications Wiring

Figure 2 illustrates one method of wiring the MCH Series LonWorks® Bus Connector with an optional switch to provide remote operation of the service pin.

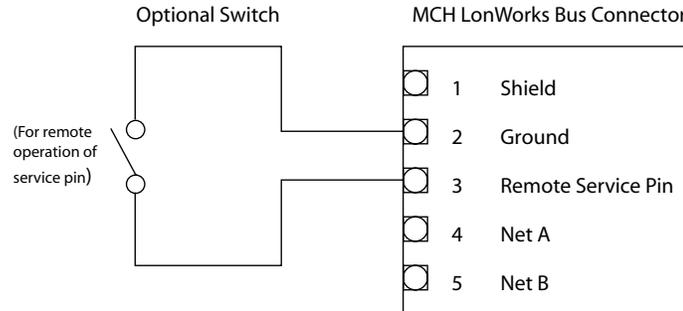
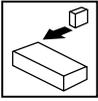


Figure 2: Wiring the MCH LonWorks® Bus Connector

- Net A, Net B** This is the 2-wire LonWorks bus designed according to the LonMark® design guidelines. The bus is of non-polarization character and supports line-powered networks.
- Service Pin** This pin is used for the (optional) remote functionality of the Service Pin pushbutton. Refer to Figure 2 for an illustration on how to wire this.
- Ground** This pin is used for the remote Service Pin functionality. Refer to Figure 2.
- Shield** This pin should be connected to the shield of the LonWorks cable, in cases where such cable is to be used. The pin is connected to the Ground terminal (2) on the communications module through an RC-filter.



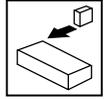
# Drive Setup & Programming

## 3 Drive Setup and Programming

Most drive parameters (including those required for serial communications) are not accessible through the LonWorks® interface. They can only be accessed by entering the Programming Mode of the drive itself. Refer to the MCH Installation and Operation Manual (MH01) for more information. The parameter information in manual MH01 is based on the standard MCH Series Modbus™ Drive. The differences between the drive programming parameters described in the manual and those that exist in the MCH Series LonWorks® Drive are explained in sections 3.1-3.4 herein.

### 3.1 Added Programming Parameters

60 SERIAL TIMEOUT	This parameter makes the serial watchdog timeout period selectable. (Section 3.5)
86 MOTOR RATED SPEED	This parameter allows the user to enter the nominal speed of the motor in RPM. This value is required for LON parameter nvoSpeedActRpm to function properly. This parameter has a minimum value of 1 RPM and a maximum value of 65000 RPM. The default is 1800 RPM.
89 MOTOR RATED FREQUENCY	This parameter allows the user to enter the nominal frequency of the motor in Hz. This value is required for many LON parameters (including nviDrvSpeedStpt and nvoDrvSpeed) to function properly. This parameter has a minimum value of 0.00 Hz and a maximum value of 650.00 Hz. The default is 60.00 Hz.
125 APP REVISION	This parameter allows the user to view the version of the application software installed in the ABS_LON module. This parameter is used for troubleshooting and to establish compatibility between the drive software and the ABS_LON module. If this parameter is displaying a value of 0104 or 9999, contact AC Tech.
126 CPI REVISION	This parameter allows the user to view the version of the common profile interface software installed in the ABS_LON module. This parameter is used for troubleshooting and to establish compatibility between the drive software and the ABS_LON module. If this parameter is displaying a value of 0124 or 9999, contact AC Tech.
127 CFG REVISION	This parameter allows the user to view the version of the AC Tech configuration software installed in the ABS_LON module. This parameter is used for troubleshooting and to establish compatibility between the drive software and the ABS_LON module. If this parameter is displaying a value of 0001 or 9999, contact AC Tech.



## 3.2 Bus Configuration Parameters

The Bus configuration parameters are only used to provide additional information about the installation state of the drive. As the address information usually is assigned from the network side in a LonWorks network, in the programming mode of the drive, these parameters are read-only.

**100 NODE STATE** This parameter contains the current state of the network interface. Configured Online is the normal run-time mode and means that the drive is commissioned and online. Soft/Bypass/Hard Offline means the node is not participating actively on the network.

Value	Node State
0	Unknown State
1	Unconfigured
2	Applicationless
3	Configured Online
4	Configured Offline
5	Soft Offline
6	Configured Bypass Offline
7	Hard Offline, Bypass Offline

- 101 NEURON ID [5]** Byte 6 of the unique Neuron ID (MSB)
- 102 NEURON ID [4]** Byte 5 of the unique Neuron ID
- 103 NEURON ID [3]** Byte 4 of the unique Neuron ID
- 104 NEURON ID [2]** Byte 3 of the unique Neuron ID
- 105 NEURON ID [1]** Byte 2 of the unique Neuron ID
- 106 NEURON ID [0]** Byte 1 of the unique Neuron ID (LSB)
- 107 NODE ADDRESS 1** Indicates the ID of the node within this subnet. A value of 0 means that it is not assigned.
- 108 NODE SUBNET 1** Indicates to which subnet this node belongs. A value of 0 means that it is not assigned.



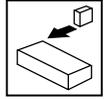
## Drive Setup & Programming

Each domain in a LonWorks network has a unique ID of 0, 1, 3 or 6 bytes in length. If the ID is shorter than 6 bytes, it is left justified in the following parameters (109-114).

109 DOMAIN ID 1 [5]	Byte 6 of the domain ID (MSB)
110 DOMAIN ID 1 [4]	Byte 5 of the domain ID
111 DOMAIN ID 1 [3]	Byte 4 of the domain ID
112 DOMAIN ID 1 [2]	Byte 3 of the domain ID
113 DOMAIN ID 1 [1]	Byte 2 of the domain ID
114 DOMAIN ID 1 [0]	Byte 1 of the domain ID (LSB)
115 NODE ADDRESS 2	Indicates the ID of the node within this subnet. A value of 0 means that it is not assigned.
116 NODE SUBNET 2	Indicates to which subnet this node belongs. A value of 0 means that it is not assigned.

Each domain in a LonWorks network has a unique ID of 0,1,3 or 6 bytes in length. If the ID is shorter than 6 bytes, it is left justified in the following parameters (117-122).

117 DOMAIN ID 2 [5]	Byte 6 of the domain ID (MSB)
118 DOMAIN ID 2 [4]	Byte 5 of the domain ID
119 DOMAIN ID 2 [3]	Byte 4 of the domain ID
120 DOMAIN ID 2 [2]	Byte 3 of the domain ID
121 DOMAIN ID 2 [1]	Byte 2 of the domain ID
122 DOMAIN ID 2 [0]	Byte 1 of the domain ID (LSB)
123 XMIT ERRORS	The number of CRC errors detected during packet reception. These may be due to collisions or noise on the transceiver input.
124 TRANS TIMEOUTS	The number of times that the node failed to receive expected acknowledgements or responses after retrying the configured number of times. These may be due to destination nodes being inaccessible on the network, transmission failures because of noise on the channel, or if any destination node has insufficient buffers or receive transaction records.

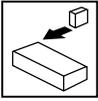


## 3.3 Omitted Parameters and Selections

36 SLEEP THRESHOLD	Sleep Mode functionality has not been added to the MCH Series LonWorks® drive so these drive parameters do not exist.
37 SLEEP DELAY	
38 SLEEP BANDWIDTH	
41 ANALOG INPUT FILTER	
52 TB14 OUT	The following options have not been added to these parameters in the MCH Series LonWorks® drive:
53 TB15 OUT	
54 RELAY	
	INV MIN/MAX A
	MIN ALARM
	INV MIN ALARM
	MAX ALARM
	INV MAX ALARM
58 SERIAL ADDRESS	The ABS_LON module only communicates with one MCH Drive so there is no need for the drive to have a unique serial address and this parameter has been removed.

## 3.4 Modified Parameters and Selections

8 ACCEL	This parameter defines the time that it will take for the drive to ramp the motor up from 0.00Hz to Drive Parameter #11 (Max Frequency).
9 DECEL	This parameter defines the time that it will take for the drive to ramp the motor down from Drive Parameter #11 (Max Frequency) to 0.00Hz.
24 AUTO SOURCE	The default selection for this parameter is KEYPAD. This setting is required if the drive speed is to be modified over the LonWorks® network.
32 HZ MULTIPLIER	The default setting for this parameter is 30.00.
56 SERIAL LOSS	The selections for this parameter are FAULT (default) and PRESET#3. The functionality of this parameter is described in Section 3.5 Serial Communications Setup.



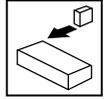
## Drive Setup & Programming

### 3.5 Serial Communication Setup

The factory default values of the drive parameters have been set to allow immediate serial communications (without serial stop/start and serial speed commands). For serial speed and/or serial start/stop control, modify the setting of Drive Parameter #30 (Control). The drive parameters that are required for serial communications, including Drive Parameter #30, are described herein.

24 AUTO SOURCE	This parameter must be set to KEYPAD for the drive speed or setpoint to be modified over the network.												
30 CONTROL	This parameter should be set to accommodate the specific application intent:  <table><tr><td>NORMAL</td><td>Serial start/stop and serial speed commands are invalid.</td></tr><tr><td>NORM NO HAND</td><td>Same as NORMAL except the HAND/OFF/AUTO, herein referred to as H/O/A, is limited to settings of OFF and AUTO.</td></tr><tr><td>SERIAL SPEED</td><td>Serial start commands are invalid. Serial speed commands are valid in AUTO.</td></tr><tr><td>S SPD/NO HAND</td><td>Same as SERIAL SPEED except H/O/A is limited to settings of OFF and AUTO.</td></tr><tr><td>SERIAL AUTO</td><td>Serial start/stop and serial speed commands are valid in AUTO. This setting forces the drive to be started via the serial link when in AUTO.</td></tr><tr><td>S AUTO/NO HND</td><td>Same as SERIAL AUTO except H/O/A is limited to settings of OFF and AUTO.</td></tr></table>	NORMAL	Serial start/stop and serial speed commands are invalid.	NORM NO HAND	Same as NORMAL except the HAND/OFF/AUTO, herein referred to as H/O/A, is limited to settings of OFF and AUTO.	SERIAL SPEED	Serial start commands are invalid. Serial speed commands are valid in AUTO.	S SPD/NO HAND	Same as SERIAL SPEED except H/O/A is limited to settings of OFF and AUTO.	SERIAL AUTO	Serial start/stop and serial speed commands are valid in AUTO. This setting forces the drive to be started via the serial link when in AUTO.	S AUTO/NO HND	Same as SERIAL AUTO except H/O/A is limited to settings of OFF and AUTO.
NORMAL	Serial start/stop and serial speed commands are invalid.												
NORM NO HAND	Same as NORMAL except the HAND/OFF/AUTO, herein referred to as H/O/A, is limited to settings of OFF and AUTO.												
SERIAL SPEED	Serial start commands are invalid. Serial speed commands are valid in AUTO.												
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SERIAL AUTO	Serial start/stop and serial speed commands are valid in AUTO. This setting forces the drive to be started via the serial link when in AUTO.												
S AUTO/NO HND	Same as SERIAL AUTO except H/O/A is limited to settings of OFF and AUTO.												

The STOP command issued when LonWorks (LON) parameter nviEmrgOvrdr is set to EMERG\_SHUTDOWN is accepted regardless of the H/O/A switch position.



- 56 SERIAL LOSS** This parameter sets the action to be taken in the event that the LON has modified the speed command or started the drive and a serial watchdog timeout occurs. The options for this parameter are FAULT (default) and PRESET#3.
- If FAULT is selected and the drive is running when a serial watchdog timeout occurs the drive will trip into a SERIAL FAULT stopping the drive and taking it out of serial control. A fault reset command (issued via LON parameter nviResetFault), a keypad stop or a terminal stop is required to clear the fault.
- If PRESET#3 is selected and a timeout occurs the drive will continue to run at the speed defined in Drive Parameter #3 (PRESET #3). If the drive is stopped (KSTOP, RSTOP, SSTOP or FAULT) or a valid speed command is received from the LON, the drive will return to its normal speed reference.
- When Drive Parameter #30 (CONTROL) is set to SERIAL SPEED, the speed reference MUST be the drive keypad (-KEY or -MKB) for the serial loss action to take effect. When CONTROL is set to SERIAL AUTO the serial loss action will take effect with any speed reference.
- This parameter also defines the action to be taken in the event that the drive is placed OFFLINE or a Receive Heartbeat timeout (RX\_FAIL) occurs.
- 57 SERIAL** This parameter needs to be set to either WITH TIMER (default) or W/O TIMER for the drive to communicate through the serial link. Serial communications will not work if this parameter is set to DISABLED.
- 60 SERIAL TIMEOUT** This parameter makes the serial watchdog timeout period selectable. It has a minimum value of 10 seconds and maximum value of 255 seconds. The default is 30 seconds. If no action is to be taken when a serial watchdog timeout occurs, Drive Parameter #57 (Serial) should be set to W/O TIMER. This will disable the watchdog timer. Otherwise Drive Parameter #57 (Serial) should be set to WITH TIMER. The action to be taken when a timeout occurs is then determined by Drive Parameter #56 (Serial Loss).
- NOTE:** Receive heartbeat timeouts and OFFLINE occurrences are not affected by the setting of Parameter 60.



# LonWorks Network Variables

## 4 MCH LonWorks® Network Variables

The MCH LonWorks® Network Variables (nv) are divided into three types: input, output and configuration. Sections 4.2 - 4.5 describe each of these variable types and the individual supported variables within each.

### 4.1 LonWorks® Network Variable Map

Figure 3 is a visual map of the supported LonWorks® network variables for the MCH Series drive.

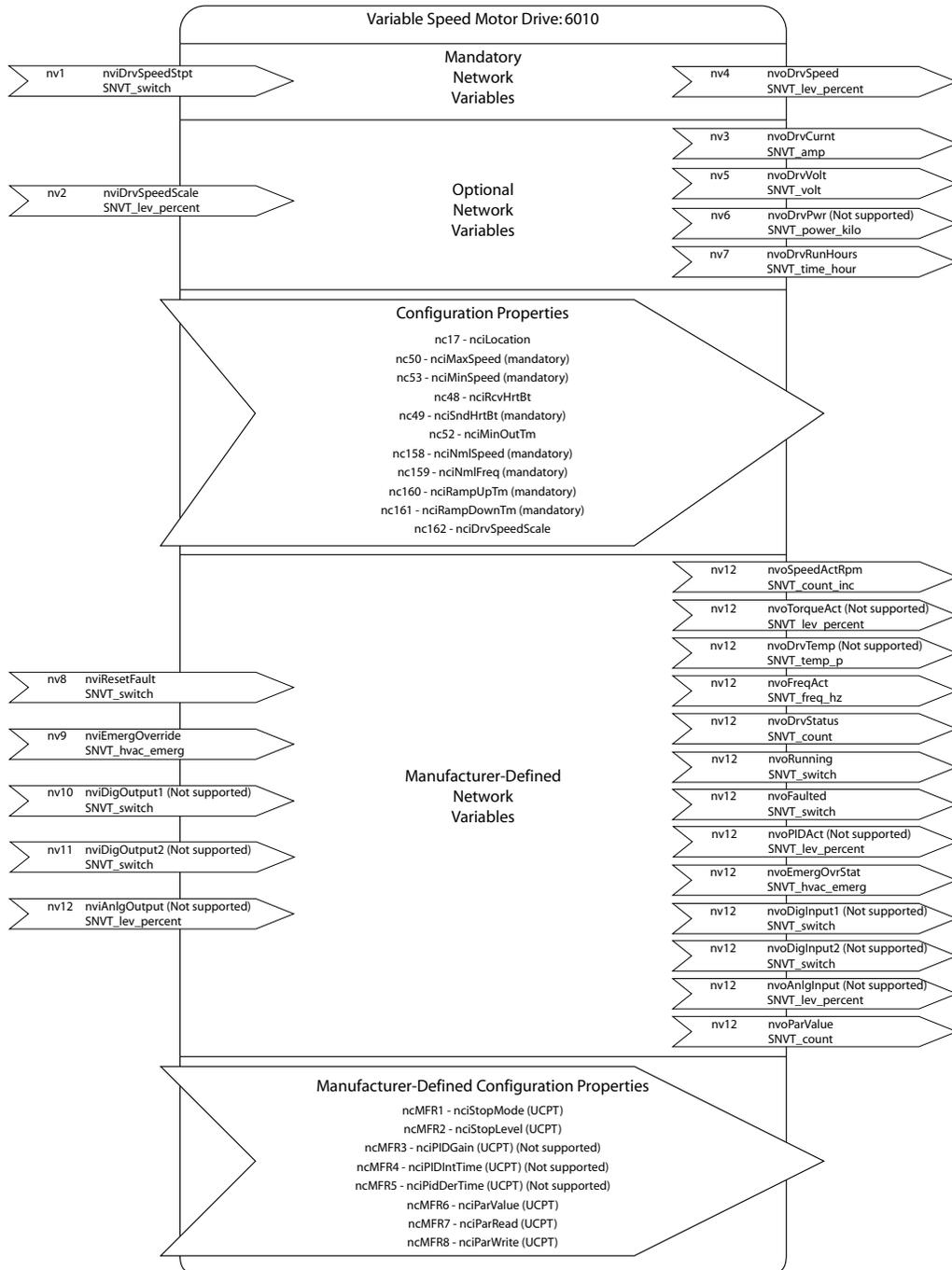
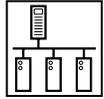


Figure 3: LonWorks® Network Variable Map for MCH Series Drives



## 4.2 Supported Input Network Variables

### NviObjRequest

**Definition** Network input SNVT\_obj\_request nviObjRequest;

**Explanation** This input is used to enable control commands and updates from the network. The status of the node is reported in nvoObjStatus.

**Valid range:**

Object Request	Function
RQ_UPDATE_STATUS	Updates nvoObjStatus
RQ_CLEAR_STATUS	Clears nvoObjStatus
RQ_CLEAR_ALARM	Resets a drive fault
RQ_REPORT_MASK	Reports supported requests in nvoObjStatus
RQ_NORMAL	The normal request. Sets object to default state
RQ_DISABLE	Stops the drive with the selected stop mode and disables the operation and object
RQ_ENABLE	Enables the drive for operation and enables the object

Commands not listed above will be reported as invalid\_request in nvoObjStatus.

### NviDrvSpeedStpt

**Definition** Network input SNVT\_switch nviDrvSpeedStpt.

**Explanation** This input network variable provides a low-resolution speed setpoint. It may also use the receive heartbeat function. The speed setpoint is the result of multiplication of nviDrvSpeedStpt and nviDrvSpeedScl.

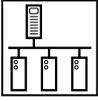
**Valid Range:**

State	Valid Range
0	Stop the drive
1	Start the drive
-1 (0xff)	Auto (Invalid)

Value (% Nominal)	Internal Value
-100.0% to -0.5%	-200 to -1
0.0%	0
0.5% to 100.0%	1 to 200

**Default value** The default value is AUTO (state = 0xFF). This value will be adopted at power-up. This network variable input may use the Receive Heartbeat function if the Receive Heartbeat function is setup for use. The actual value of drive speed also depends on the setting of nviDrvSpdScl.



## LonWorks Network Variables

### NviDrvSpdScl

- Definition** Network input SNVT\_lev\_percent nviDrvSpeedScale
- Explanation** This input network variable provides scaling for nviDrvSpeedStpt (0.005% resolution).
- For example, if the value of nviDrvSpeedStpt is 100% and nviDrvSpdScl value is 150%, then the actual speed setpoint value is 150% meaning that the drive should run at 1.5 times nominal speed in the forward direction. A negative value for nviDrvSpdScl sets the drive direction to reverse.
- For example if nviDrvSpeedStpt value is 100% and nviDrvSpdScl value is -150%, then actual speed setpoint value is -150%, meaning that the drive should run at 1.5 times nominal speed in the reverse direction.
- Valid Range** -163.840% to 0.00 % or 0.00% to +163.835%  
The value 0x7FFF represents invalid data.
- Default Value** Defined by nciDrvSpdScl.

### NviResetFault

- Definition** Network input SNVT\_switch nviResetFault
- Explanation** This input network variable provides a mechanism to clear a fault status in the drive.

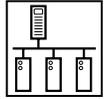
**Valid Range:**

State	Value	Command
0	0.0%	Reset Fault Ready
1	100.0%	Reset Fault

On a transition from 0 to 1, this input network variable clears the fault condition in the drive. Following a fault reset, this variable must be set back to 0 to enable the next fault reset.

- Default Value** The drive will power-up in the 'Reset Fault Ready' state.

# LonWorks Network Variables



## NviEmrgOvrd

**Definition** Network input SNVT\_hvac\_emerg nviEmrgOvrd

**Explanation** HVAC Emergency Mode. This input network variable provides the ability to stop the motor in case of an emergency.

**Valid Range:**

Setting	Function
EMERG_NORMAL	Not emergency mode, motor control enabled
EMERG_PRESSURIZE	No functionality in this implementation
EMERG_DEPRESSURIZE	No functionality in this implementation
EMERG_PURGE	No functionality in this implementation
EMERG_SHUTDOWN	Emergency shutdown mode. Stops motor
EMERG_FIRE	No functionality in this implementation
EMERG_NUL	Value not available

**Default Value** EMERG\_NORMAL

## 4.3 Supported Output Network Variables

### NvoObjStatus

**Definition** Network output SNVT\_obj\_status nvoObjStatus

**Explanation** This nvo reports the node object status.

**Valid Range:**

Bit Setting	Function
Invalid_id	Invalid node ID requested
report_mask	Reporting supported fields
Disabled (20)	RQ_DISABLED is active
electrical_fault (5)	Same as the faulted bit in nvoDrvStatus
In_alarm	Same as the alarm bit in nvoDrvStatus

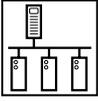
### NvoDrvSpeed

**Definition** Network output SNVT\_lev\_percent nvoDrvSpeed

**Explanation** This output network variable provides the speed of the drive as a percentage of the nominal speed.

**Valid Range** -163.830% to 0.000 % or 0.000% to +163.830%.  
The value 0x7FFF represents invalid data.

**Default Value** 0.000%.



## LonWorks Network Variables

### NvoDrvCurnt

**NOTE:** This parameter is not supported in drives with software version MC11101 or MC11102.

Definition Network output SNVT\_amp nvoDrvCurnt

Explanation This output network variable provides the drive output current in Amps.

Valid Range 0.0 to 3276.7 A

Default Value 0.0 A

### NvoDrvRunHours

**NOTE:** This parameter is not supported in drives with software version MC11101 or MC11102.

Definition Network output SNVT\_time\_hour nvoDrvRunHours

Explanation This output network variable provides total operation time of the motor in hours.

Valid Range 0 to 65535 hours

Default Value 0 hours

### NvoDrvVolt

**NOTE:** This parameter is not supported in drives with software version MC11101 or MC11102.

Definition Network output SNVT\_volt nvoDrvVolt

Explanation This output network variable provides the drive output voltage in Volts.

Valid Range 0 – 700 V

Default Value 0 V

### NvoSpeedActRpm

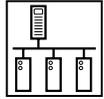
Definition Network output SNVT\_count\_inc nvoSpeedActRpm

Explanation This output network variable provides the speed of the drive in RPM's

Valid Range -32768 to 0 or 0 to 32767

Default Value 0 RPM

# LonWorks Network Variables



## NvoFreqAct

Definition	Network output SNVT_freq_hz nvoFreqAct
Explanation	This output network variable provides the speed of the drive in Hz.
Valid Range	0.0 - 120.00 Hz
Default Value	0.00 Hz

## NvoDrvStatus

Definition	Network output SNVT_state nvoDrvStatus
Explanation	This output network variable provides the status of the drive.
Valid Range	

Bit	Name	Description
0	FWD	The drive is currently running the motor in forward motion
1	REV	The drive is currently running the motor in reverse motion
2	NETCTRL	The network is the active source for start/stop control
3	NETREF	The network is the active source for the speed reference
4	RTSO	Not used
5	FAULT	The drive is currently faulted
6	ALARM	Not used
7	REF	The drive is running the motor at the speed defined by the speed reference of the active control source (i.e. actual drive speed = commanded drive speed)
8	FORN	Not used
9	ZERO SPEED	The drive is running at zero speed
10	LIMIT	Not used
11	ACC	The drive is currently ramping up to its commanded speed
12	DEC	The drive is currently ramping down to its commanded speed
13-15	Not used	Not used

Default Value 0



## LonWorks Network Variables

### NvoRunning

Definition Network output SNVT\_switch nvoRunning  
Explanation This output indicates whether or not the motor is running.  
Valid Range:

State	Value	Command
0	0.0%	The motor is not running
1	100.0%	The motor is running

Default Value 0

### NvoFaulted

Definition Network output SNVT\_switch nvoFaulted  
Explanation This output indicates whether or not the drive is currently faulted.  
Valid Range:

State	Value	Command
0	0.0%	The drive is not faulted
1	100.0%	The drive is faulted

Default Value 0

### NvoEmrgOvr Stat

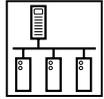
Definition Network output SNVT\_hvac\_emerg nvoEmrgOvrStat  
Explanation Feedback for the nviEmrgOvr  
Valid Range:

Value	Function
EMERG_NORMAL	Not emergency mode, motor control enabled
EMERG_SHUTDOWN	Emergency shutdown mode. Motor stopped.

Default Value EMERG\_NORMAL

### NvoParValue

Definition Network output SNVT\_count nvoParValue  
Explanation This variable contains the data read at the parameter set by nciParRead.  
Valid Range 1 - 46  
Default Value 0



## 4.4 Supported Configuration Network Variables

### NciSndHrtBt

Definition	Network config input SNVT_time_sec nciSndHrtBt
Explanation	This input configuration network variable provides the maximum send time for the variable nvoDrvSpeed.
Valid Range	0.0 to 6553.5 sec The value 0 disables the Send Heartbeat mechanism. The value 0xFFFF represents invalid data.
Default Value	0 sec (disabled)

### NciRcvHrtBt

Definition	Network config input SNVT_time_sec nciRcvHrtBt
Explanation	This configuration property is used to control the maximum time that elapses after the last update to input network variables nviDrvSpeedStpt or nviDrvSpdScI. If a timeout occurs, the module indicates an RX_FAIL condition to the drive which induces the Serial Loss action described in Section 3.5.
Valid Range	0.0 to 6553.5 sec The value 0xFFFF represents invalid data. The value 0 disables the Receive Heartbeat mechanism.
Default Value	0 sec (disabled)

### NciMinOutTm

Definition	Network config input SNVT_time_sec nciMinOutTm
Explanation	This input configuration network variable controls the minimum period of time that expires before the network output variables can be propagated (resent).
Valid Range	0.0 to 6553.5 sec The value 0xFFFF represents invalid data. The value 0 disables transmission limiting.
Default Value	0.0 sec (disabled)



## LonWorks Network Variables

### nciNmISpeed

Definition	Network config input SNVT_rpm nciNmISpeed
Explanation	This configuration property is used to provide the nominal speed of the motor.
Valid Range	1 to 65000 RPM The value 0xFFFF represents invalid data.
Default Value	1800 RPM

### nciNmIFreq

Definition	Network config input SNVT_freq_hz nciNmIFreq
Explanation	This configuration property is used to provide the nominal frequency of the motor.
Valid Range	0.0 - 650.00 Hz
Default Value	60.00 Hz

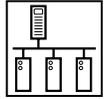
### nciMinSpeed

Definition	Network config input SNVT_lev_percent nciMinSpeed
Explanation	This configuration property is used to define the minimum speed of a motor. Its value is entered as a percentage of nominal speed, as defined by the Nominal Speed (nciNmISpeed) configuration value. The value of the minimum speed must be validated against the value of the maximum speed as follows: -163.840% <= minimum speed <= maximum speed <= 163.835%
Valid Range	-163.840% to 0.000 % or 0.000% to +163.835% The value 0x7FFF represents invalid data.
Default Value	0.830%

### nciMaxSpeed

Definition	Network config input SNVT_lev_percent nciMaxSpeed
Explanation	This configuration property is used to define the maximum speed of a motor. Its value is entered as a percent of nominal speed, as defined by the Nominal Speed (nciNmISpeed) configuration value. The value of the maximum speed must be validated against the value of the minimum speed as follows: -163.840% <= minimum speed <= maximum speed <= 163.835%
Valid Range	-163.840% to 0.000 % or 0.000% to +163.835% The value 0x7FFF represents invalid data.
Default Value	100.000%

# LonWorks Network Variables



## nciRampUpTm

Definition	Network config input SNVT_time_sec nciRampUpTm
Explanation	This configuration property is used to set the ramp up time of the drive (i.e. the time that it will take for the drive to ramp the motor from 0.00Hz to Max Frequency).
Valid Range	0.1 to 3600.0 sec (Refer to MCH Installation and Operation Manual for the actual minimum boundary) The value 0xFFFF represents invalid data.
Default Value	30.0 sec

## nciRampDownTm

Definition	Network config input SNVT_time_sec nciRampDownTm
Explanation	This configuration property is used to set the ramp down time of the drive (i.e. the time that it will take for the drive to ramp the motor from Max Frequency to 0.00Hz).
Valid Range	0.3 to 3600.0 sec (Refer to MCH Installation and Operation Manual for the actual minimum boundary) The value 0xFFFF represents invalid data.
Default Value	30.0 sec

## nciLocation

Definition	Network config input SNVT_str_asc nciLocation
Explanation	This configuration property can optionally be used to provide more descriptive physical location information than can be provided by the Neuron Chip's 6-byte location string. The location relates to the object and not to the node.
Valid Range	31 characters
Default Value	Empty spaces

## nciDrvSpdScl

Definition	Network config input SNVT_lev_percent nciDrvSpeedScale
Explanation	Default value for nviDrvSpdScl.
Valid Range	-163.840% to 0.000 % or 0.000% to +163.835% The value 0x7FFF represents invalid data.
Default Value	100.000%



## LonWorks Network Variables

### nciStopMode

Definition Network config input SNVT\_switch nciStopMode

Explanation This input network variable is used to choose between coast and ramp stop.

Valid Range:

State	Value	Command
0	0.0%	Coast to stop
1	100.0%	Ramp to stop

Default Value 0

### nciStopLevel

Definition Network config input SNVT\_lev\_percent nciStopLevel

Explanation This is the stop level for the drive when it is in ramp to stop mode. When the drive is ramping to a stop and reaches this level, a coast to stop is performed. The value is relative to nvoDrvSpeed ( i.e. a value of 5% corresponds to a nvoDrvSpeed value of 5%).

Valid Range -163.840% to 0.00 % or 0.00% to +163.835%  
The value 0x7FFF represents invalid data.

Default Value 5.000 %

### nciParValue

Definition Network config input SNVT\_count\_inc nciParValue

Explanation This nci is used as a value input for the user selected parameter nciParWrite.

Valid Range 1 - 46

Default Value 0

### nciParRead

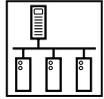
Definition Network config input SNVT\_count nciParRead

Explanation Chooses the parameter value to be read from the drive.

Valid Range 1 - 46

Default Value 0

# LonWorks Network Variables



## nciParWrite

Definition	Network config input SNVT_count nciParWrite
Explanation	Chooses the parameter value to be written to the drive.
Valid Range	1 - 46
Default Value	0

## 4.5 LonWorks XIF Files

The LonMark external interface (or XIF) file is used to set up a LonWorks network with an MCH Series drive that has not yet been commissioned. These files are available for download in the Technical Library of the Lenze-AC Tech website.

Use Drive Parameter #63 to retrieve the software version of your MCH drive. Drives with software versions MC11103 and later, and MC121xx use the 21312203.XIF file. If your MCH drive has an earlier software version (MC11101 or MC11102), then contact technical support for the appropriate XIF file.

## 4.6 Reference and Links

MCH Series Variable Frequency Drives visit:

<http://www.lenze-actech.com>

LonWorks and Echelon Corporation visit:

<http://www.echelon.com>

LonMark Functional Profiles (including 6010) visit:

<http://www.lonmark.org>

ANYBUS-S Drive Profile Embedded Interface Cards, LonMark 6010 Functional Profile visit:

<http://www.anybus.com/products/abs.shtml>

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[www.lenze-actech.com](http://www.lenze-actech.com)

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