



**Customer: Lenze BO**

Contacts: Lenze

Phone:

E-mail:

**Project:**

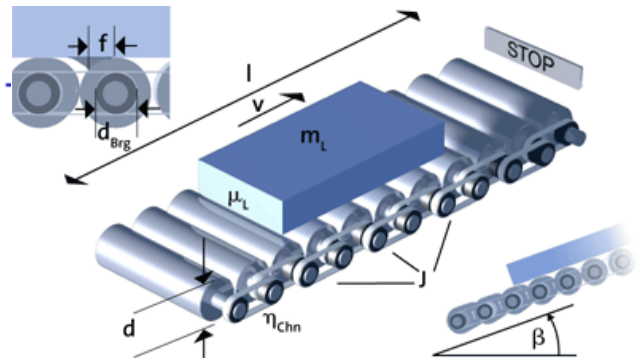
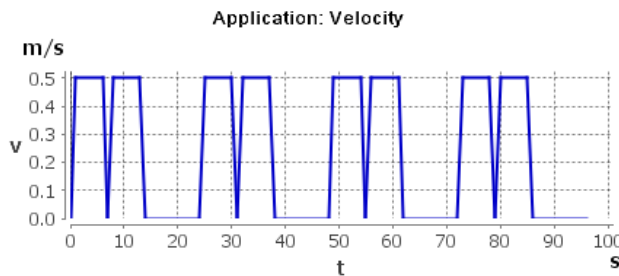
Drive axis: Rollenförderer 2000kg 0,5m/s 0,5m/s<sup>2</sup>

**Roller conveyor**

Diameter of the transport rolls	d	89.0 mm
Leverage of rolling friction	f	1.20 mm
Chain efficiency	$\eta_{\text{Chn}}$	0.990
Bearing diameter	$d_{\text{Brg}}$	100 mm
Number of wrapped chain turns	$N_{\text{Chn}}$	14
Moment of inertia of transport rollers	J	1.00E-04 kgm <sup>2</sup>
Angle of tilt	$\beta$	0 °
Coefficient of friction of load/roll		
Coefficient of friction of the bearing	$\mu_{\text{Brg}}$	2.00E-03

**Kinematic key data**

Cycle time	t	96.0 s
Max. velocity	$v_{\text{max}}$	0.500 m/s
Max. acceleration	$a_{\text{max}}$	0.500 m/s <sup>2</sup>
Max. mass in motion	$m_{\text{sum,max}}$	2000 kg



**Electrical supply and ambient conditions**

Electrical supply system

Max. motor/inverter ambient temperature

Site altitude

		3AC 400 V 50 Hz
$\vartheta_{\text{opr}}$		30 °C / 40 °C
h		1000 m

**Calculated requirement of the application**

Max. working point

Effective base process power of the application

Moment of inertia application

Max. load-matching factor

$opr_{\text{max}}$		107 1/min / 80.6 Nm / 0.905 kW
$P_{\text{rms,cto}}$		0.221 kW
$J_{\text{min}} / J_{\text{max}}$		1.00E-04 kgm <sup>2</sup> / 3.96 kgm <sup>2</sup>
$K_{J,\text{max}}$		18

**Selected products**

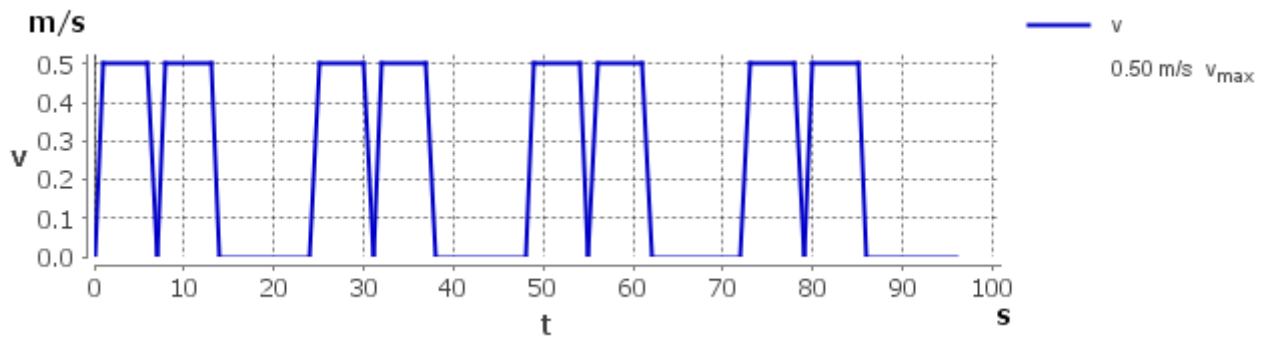
**Rated data**

**Utilisation**

	Rated data	Utilisation	
		Thermal	Maximum
Motor	1 x MSEMXX063-42 $P_N, n_N, M_N$	54 %	
Gearboxes	1 x g500-B110 (Direct mounting) $i_G, M_{\text{per,out}}$	27 %	79 %
Additional drive element	1 x Chain --- ( $i=1.07$ )	31 %	57 %
Integrated brake transistor		P	0.04 %
Brake resistor	1 x 10W / 400 $\Omega$		2 %
Electromechanical brake	without brake		
Feedback	without		



Application: Velocity



Application: Mass in motion

